

Development of Differential Amplifier Based the Second Generation Current Conveyors

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ABSTRACT

In this article, developments of Second Generation Current Conveyors (CCII) that are realized by based on the use of a differential amplifier (diff-amp) as a circuit building block are reviewed. The basic concepts of current conveyor are firstly outlined. One of the first CMOS-based promising techniques to implement CCII that proposed by Surakamponporn et al. is reviewed [9-11]. The applications of Surakamponporn's CCII as basic circuit building blocks to realize analog circuits and systems and the modifications methods to provide multiple outputs CCII are outlined and discussed. Based on feedback mechanisms, diff-amp-based CCII that are designed by modified from the CCII are also outlined and discussed. In order to understand the improvement, the characteristics of the CCII that have been compared through simulation results by Hassanenin et al. [11] are presented. Finally, the concept of chemical current conveyor (CCCII) is also noted.

1. INTRODUCTION

In the past analog signal processing performs a signal processing through a voltage signal (voltage mode). Research in analog integrated circuit design has recently gone in the direction of low power low voltage applications, especially in the environment of portable systems where power supply are driven by a single cell low voltage battery. Therefore, traditional voltage mode techniques are going to be replaced by the current mode approach.

Second generation current conveyor (CCII) has shown to be one of the major basic circuit building blocks for current-mode signal processing, in particular for low power and low voltage applications [1-8]. Analog active circuit systems can be realized by a suitable connection of one or two CCII [1-8]. Until now, a wide number of CMOS-based current conveyor circuits have been proposed in literatures. But, however, in this work only current conveyor that realized

by based on the employment of a differential pair as circuit building block will be considered [9-11].

2. SECOND GENERATION CURRENT CONVEYOR

2.1 Basic principle

A first generation current conveyor (CCI) was firstly introduced by Sedra and Smith in 1968 [7]. Later, a second generation current conveyor (CCII) was proposed by A. Sedra and K.C. Smith in 1970 [8]. The CCII has proven to be a more useful building block for active filter design and signal processing applications than the CCI. Shown in the block diagram of Fig. 1, a CCII is a three port network that the relations of the voltages and currents of the ports can be defined in the form of hybrid parameter as

$$\begin{bmatrix} i_Y \\ V_X \\ i_Z \end{bmatrix} = \begin{bmatrix} 0 & 0 & 0 \\ 1 & 0 & 0 \\ 0 & \pm 1 & 0 \end{bmatrix} \begin{bmatrix} V_Y \\ i_X \\ V_Z \end{bmatrix} \quad (1)$$

where, the plus and minus signs denote positive and negative current, respectively. On the other hand, we can rewrite the eq. (1) as

$$i_Y = 0, V_Y = V_X \quad \text{and} \quad i_Z = \pm i_X \quad (2)$$

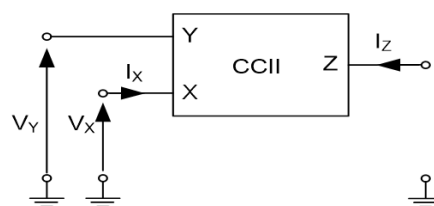


Fig.1: Block diagram of CCII.

From eq. (2), we can be inferred that the voltage of the low impedance port X follows the voltage at high impedance port Y. The current flowing at port Z is proportional to the current flowing into the port X.

2.2 Differential-pair-based CCII circuits

Fig. 2 shows the circuit diagram of the first possible solution of CMOS-based CCII that was proposed by Surakamponporn et al. [9]. In fact, this is a CMOS-based version of the bi-polar based voltage to current converter circuit that introduced by Pookaiyaudom et al. [12]. The circuit is operated

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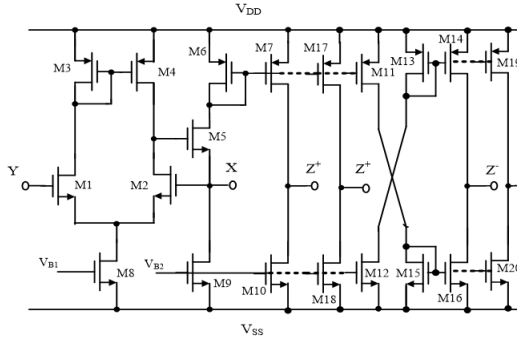


Fig.4: Multiple Outputs CCII [21-26].

transistors [29], were also proposed.

3.3 CCIIs with Improved Performance

Some of new CCII that based on the modification of the circuit structure of the Fig. 2 are outlined in this section. Different feedback mechanisms around diff-amp were proposed to force $V_{GS1} \approx V_{GS2}$. In 1992, the CCII of Fig. 5(a) was proposed by Laopoulos et al., where M5, M6, M12 and M13 form as high loop gain feedback part to provide low r_X [30]. A simple CCII as shown in Fig. 5(b) was proposed by Palmisano and Palumbo in 1995 [31]. This CCII, M1 of the diff-amp is driven by the constant current I_B from M3, while M4 forms as a common to feedback the current I_B to diode-connected M2.

In stead of using regular current mirror, R. Wojtyna employed a special regular cascade current mirror in order to design the CCII to operate for $\pm 3V$ supply voltage [32]. A differential difference CCII with its applications was proposed by W. Chiu et al. in [33]. A voltage conveyor that was obtained on the basis of the CCII in the Fig. 2 was described by I.M. Filanovsky in reference 34. S. Emami et al. proposed a new circuit structure that can be configured as CCII+ and/or CCII- without needing an additional current mirror in [35]. A class-A CMOS CCII suitable for high frequency applications based on the used of flipped voltage follower was presented by Hassanein et al. [36]. The simulations results and a fair comparison between the proposed CCII and Surakamponorn CCII were also given. Last but not least, a low power second generation current conveyor circuit allows measuring the mechanical frequency response of the nanocantilever structure in the megahertz range was proposed in [37].

3.4 Others Differential Amplifier Based CCII circuits

The CCII with the circuit structure similar to the Fig.2 was proposed by Liu et al. as shown in Fig. 5(c), but the PMOS common sources M5 is used to feedback to port X instead [38]. The weak point is

that Liu's CCII gives low offset only for the case that signal current i_X is small. Fig. 5(d) shows the CCII using two diff-amp stages was proposed by Ismail and Soliman, where the feedback path is similar to the circuit of Fig. 5(b) [39]. Fig. 5(e) shows a high precision CCII that proposed by Yodprasit [40], where two feedback paths to port X, through M5 and M6, were used. Due to the feedbacks, the offset voltage of Yodprasit's CCII is very low and not depends on i_X . But, however, due to too much feedback to port X, bandwidth of the circuit is quite low. Later on Hassan and Soliman have improved this problem by adding of source follower sections at the input stage [41]. In addition, H.O. Elwan et al. was introduced a class-A CMOS CCII that can work with single supply voltage. This CCII was then modified to work as a class AB while maintaining the rail to rail swing capability as shown in Fig. 5(f).

Table 1 shows the comparison of the performance of the CCII of Fig. 2 and Fig. 5 that were studied by Hassanein et al. [11]. We can see that Surakamponorn's CCII of Fig.2 provides a moderate characteristic with high values of offset. Yodprasit's CCII of Fig 5(f) provides the good performance but with narrow bandwidth. Current conveyors of the Fig. 5(b), Fig. 5(c) and Fig. 5(f) give large bandwidth but r_X are quite large.

4. MODIFICATION OF CCII DEFINITION

4.1 Electronically tunable CCII

An electronically tunable CCII (ECCII) was proposed by Surakamponorn and Thitimasjshima in 1988, where its voltages and currents of the ports can be defined in the form of hybrid parameter as [43]

$$\begin{bmatrix} i_Y \\ V_X \\ i_Z \end{bmatrix} = \begin{bmatrix} 0 & 0 & 0 \\ 1 & 0 & 0 \\ 0 & \pm A_0 & 0 \end{bmatrix} \begin{bmatrix} V_Y \\ i_X \\ V_Z \end{bmatrix} \quad (7)$$

Later on, in 1992, Surakamponorn and Kumwachara proposed an electronically tunable CMOS ECCII, by co-operate a small signal current gain stage with the CCII in the Fig.2 in order to adjust the current gain by electronic means [43-44]. This building block will allow easy realization of analog functions with controlled characteristics.

The circuit of Fig. 6 was employed to realize electronically tunable current-mode biquadratic active filters [45,-47]. Also, by this new concept, new ECCII have been proposed in the literatures [48-53].

4.2 Chemical Current Conveyor

Recently, Pookaiyaudom et al. have propose the concept of chemical current conveyor (CCCII) by integrate ISFET (Ion-Selective Field Effect Transistor) which is a chemical sensor with the CCII circuit [51-54]. The characteristic of the CCCII and it block diagram are shown in the Fig. 7. From the figure,

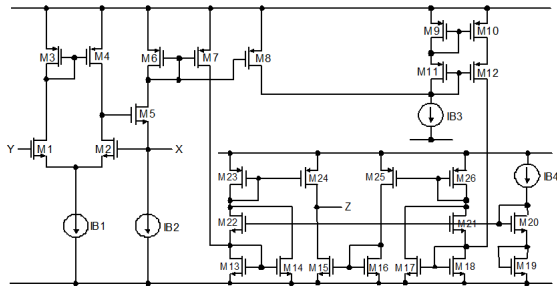
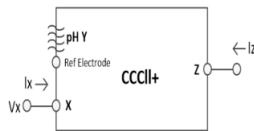


Fig. 5: CMOS-based ECCII [43].

since the chemical sensor ISFET is attached to port Y, the voltage at the low impedance port X will follow the voltage of the high impedance PH-Y port and the current of port X is transfer to the output port Z. Usually, the output of the CCCII is in the form of current or voltage that is related to the pH value. However, if a computing circuit is cooperating, the output value can also be arranged in the form that related to the time integral or time derivative value.

$$\begin{bmatrix} i_{pH} \\ V_X \\ i_Z \end{bmatrix} = \begin{bmatrix} 0 & 0 & 0 \\ 1 & 0 & 0 \\ 0 & 1 & 0 \end{bmatrix} \begin{bmatrix} V_{pH} \\ i_X \\ V_Z \end{bmatrix} \quad (8)$$

6(a) Hybrid parameter



6(b) Block diagram [52,53]

Fig. 6: Positive CCCII+.

5. CONCLUSION

In this article, one of the first CMOS-based CCII that implemented by based on the use of long tail pair differential amplifiers is reviewed. The applications of the CCII as basic circuit building blocks and the modifications to be multiple outputs CCIIs are outlined. Differential-amplifier-based CCII circuits that are designed by modified from Surakamponorn et al. CCII are also discussed.

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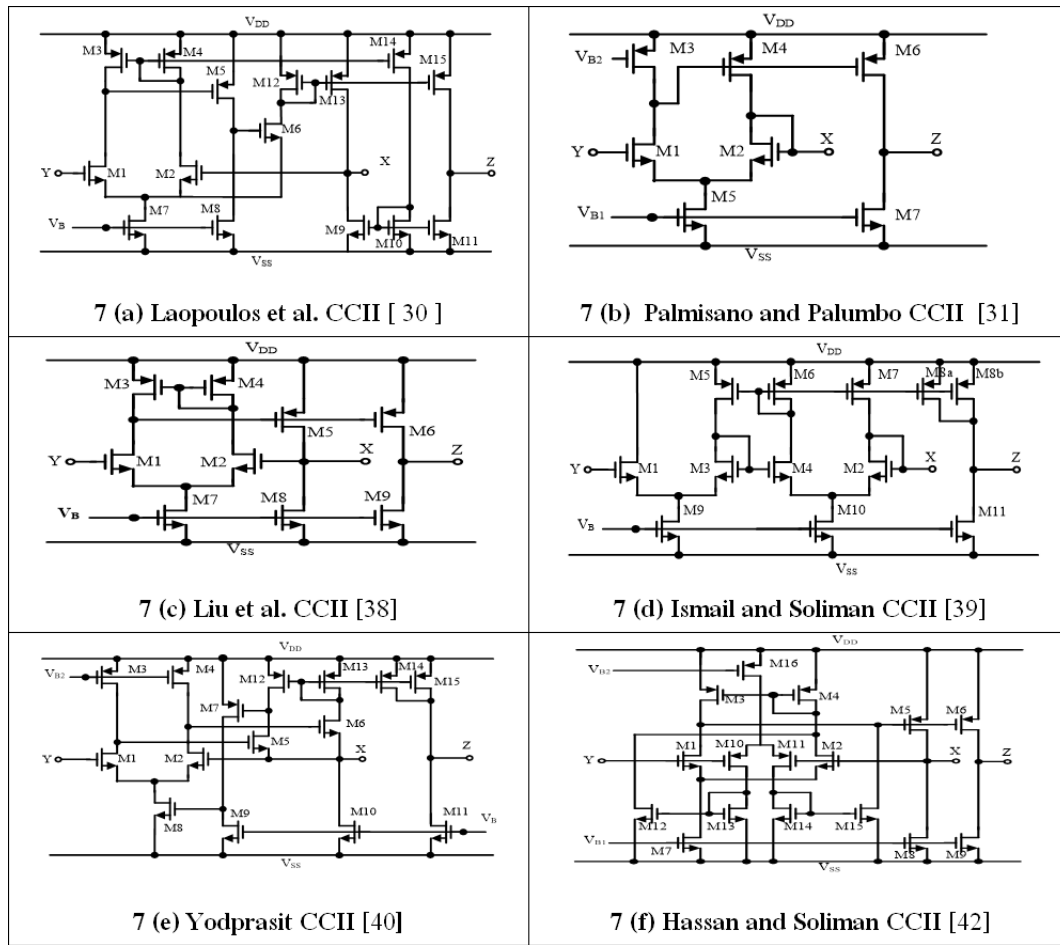


Fig.7: Diff-amp Based Second Generation Current Conveyors.

Table 1: Comparison of the CCII performances [11].

Parameter	unit	Fig. 2	Fig. 5(a)	Fig. 5(b)	Fig. 5(c)	Fig. 5(d)	Fig. 5(e)	Fig. 5(f)
Input Voltage range	V	-0.73 to 0.2	-0.5 to 0.7	-0.3 to 0.7	-0.5 to 0.8	-0.4 to 0.9	-0.5 to 0.2	-1.46 to 0.85
A_V (Average values)	-	0.99385	0.99996	1.00014	0.99998	0.989	0.999998	0.99995
Voltage offset variation	mV	-4.52 to 2.27	-0.066 to -0.007	-0.642 to 0.506	-0.078 to -0.056	-4.77 to 12.34	-0.0025 to -0.00047	-0.771 to -0.043
F_{3db} of voltage transfer gain	MHz	776	2.7	1800	1660	589	7.5	1995
Input current range	μA	-100 to 100	-150 to 150	-100 to 100	-100 to 100	-200 to 200	-100 to 100	-100 to 100
A_I (Average values)	-	1.0037	0.99998	0.9946	0.99991	1.0038	1.01034	0.99995
Current offset variation	μA	-1.04 to -0.0006	-0.001 to 0.0036	0.583 to 2.35	-0.0035 to 0.006	1.05 to 3.08	-2.2300 to -0.044	-0.004 to 0.0058
F_{3db} of current transfer gain	MHz	66	23	94.5	95	66.8	6.6	115
r_X	Ω	5.9	3.5	14.63	10.46	6.92	0.1	9.14

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